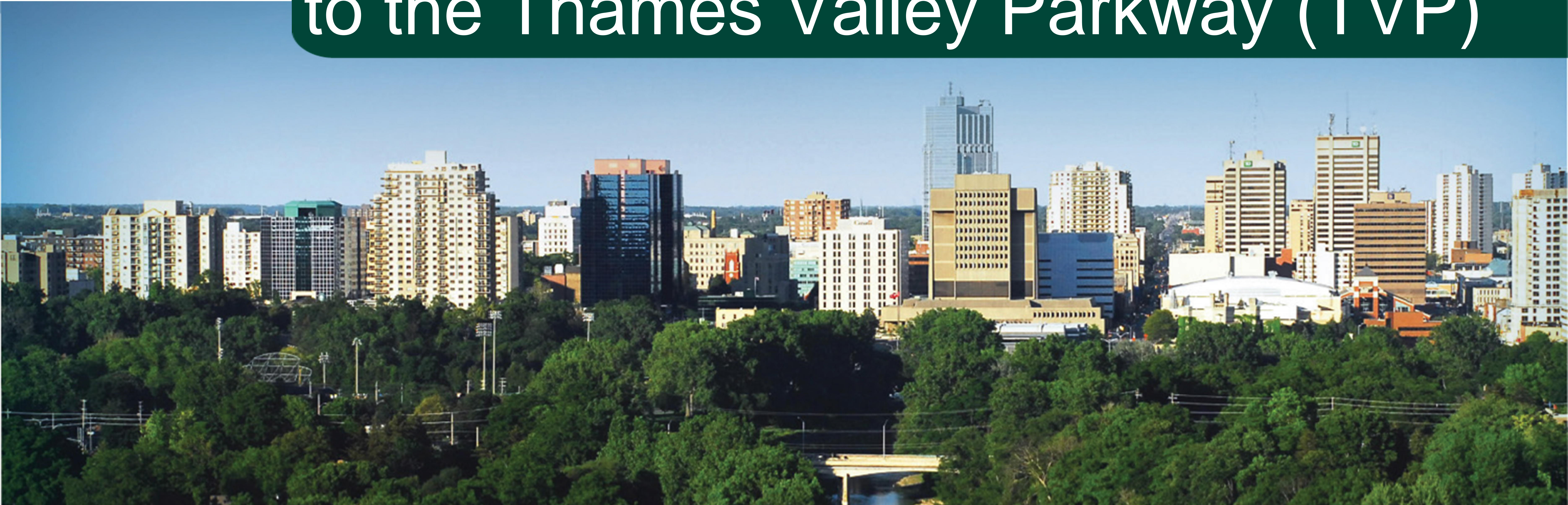




Stoney Creek Pathway Connection to the Thames Valley Parkway (TVP)

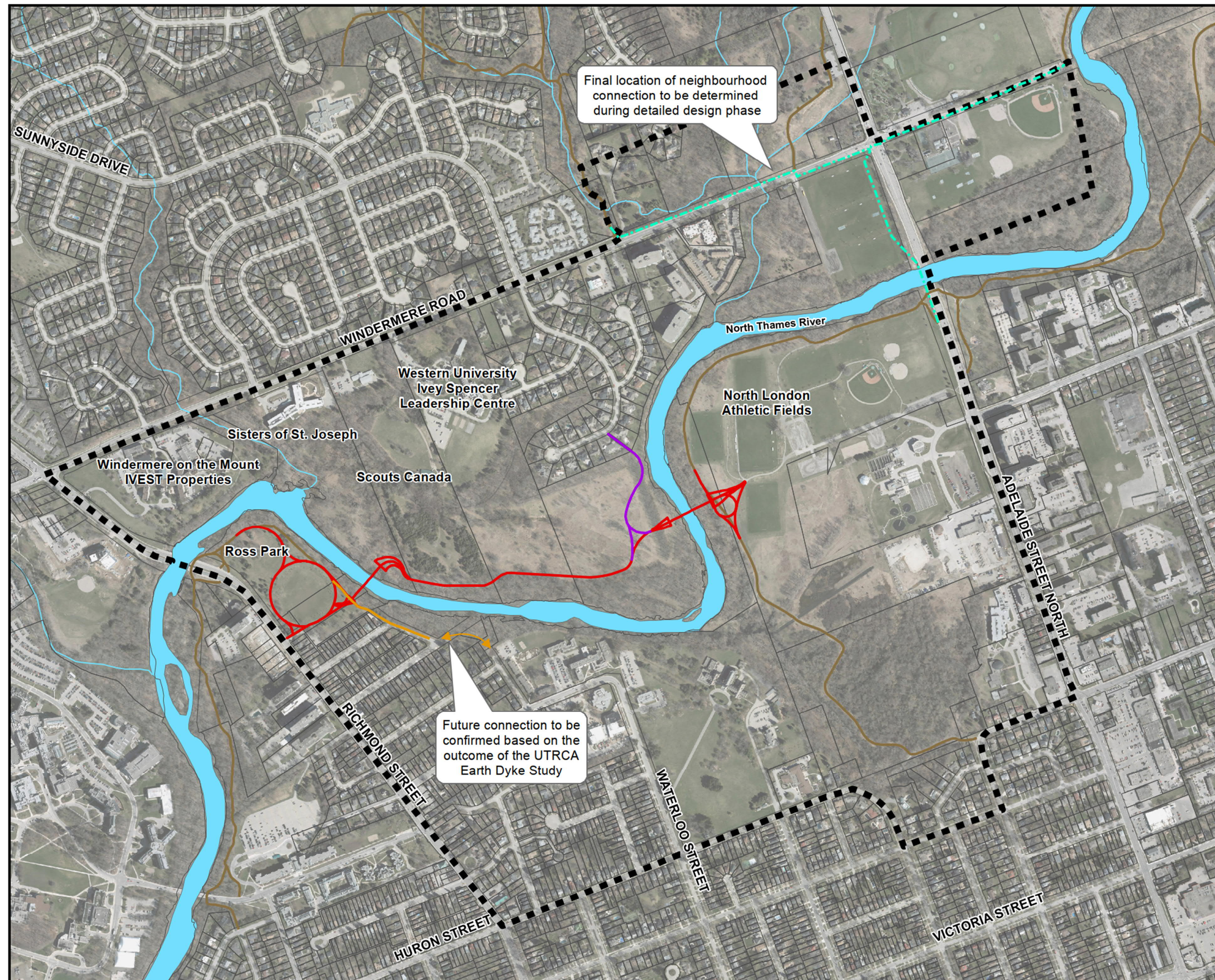


Integrated Transportation Community Advisory Committee
April 17, 2024





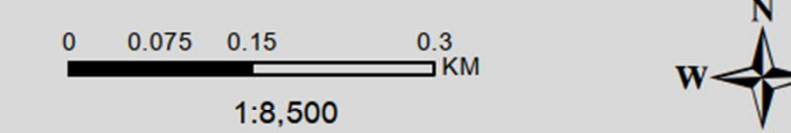
Project Background -TVP North Branch



City of London
Thames Valley Parkway North Branch Connection,
Richmond Street to Adelaide Street
Municipal Class Environmental Assessment

Environmental Screening Report
Preferred Route
Figure E-1

- Tetherwood Neighbourhood Connection & Emergency Access
- Glenora/Stoney Creek Neighbourhood Connection
- Broughdale/North London Neighbourhood Connection
- TVP Preferred
- Existing Thames Valley Parkway
- Study Area
- Property Parcels



MAP DRAWING INFORMATION:
DATA PROVIDED BY THE CITY OF LONDON
MAP CREATED BY: B.J.F.
MAP CHECKED BY: S.N.S.
MAP PROJECTION: NAD 1983 UTM Zone 17N

FILE LOCATION: G:\GIS\141084 - Thames Valley Parkway.mxd



PROJECT: 14-1084
STATUS: FINAL
DATE: 02-22-2016

The TVP North Branch project filled a gap in the pathway system between Ross Park and North London Athletic Fields. Construction was completed in 2020.

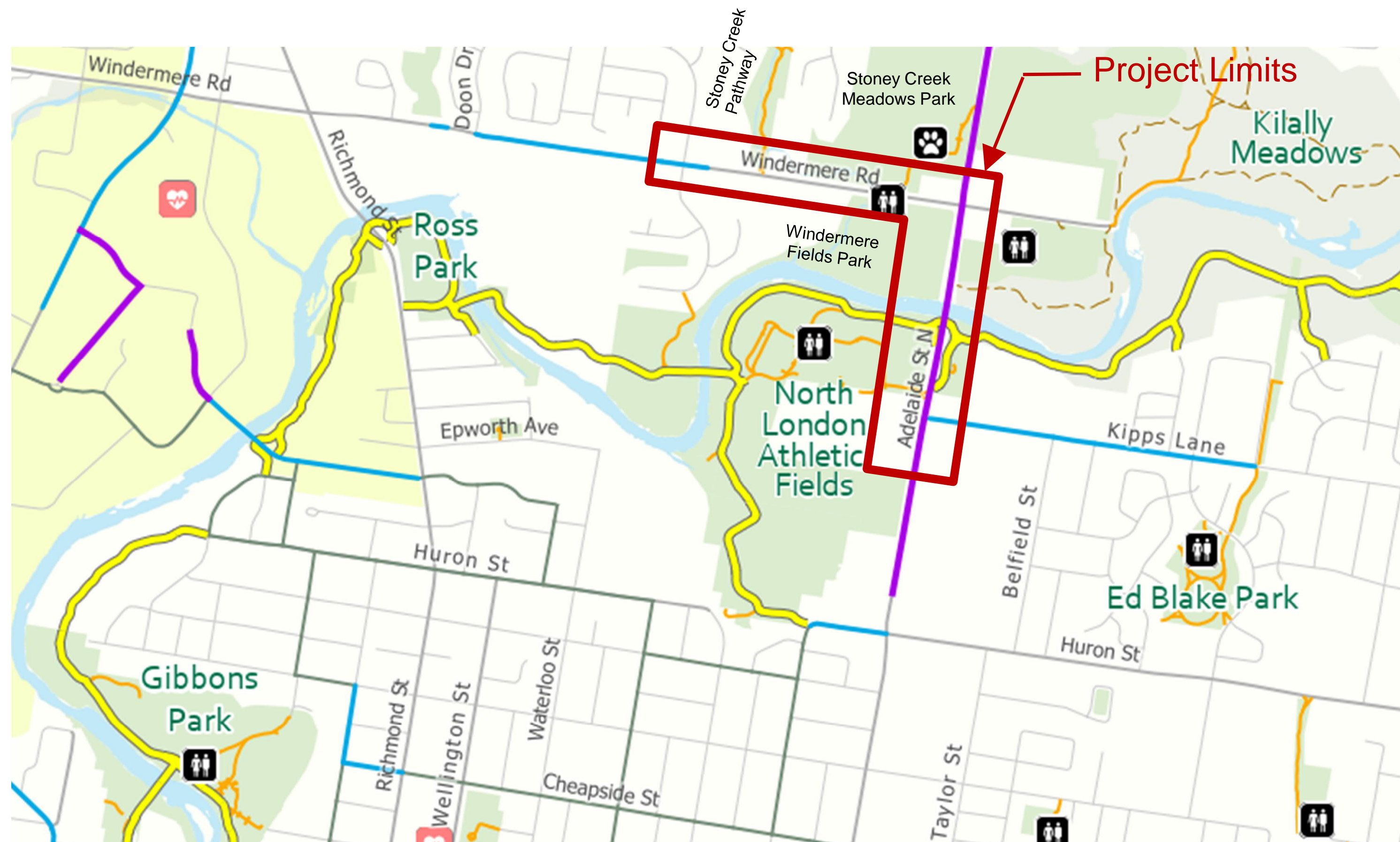
The Environmental Assessment (EA) completed for that project identified several future neighbourhood connections. The City is now moving ahead with one of these connections, referred to in the EA as the “Glenora/Stoney Creek Neighbourhood Connection”.

This project will connect the Stoney Creek Pathway to the TVP North Branch with a continuous multi-use pathway.

The section of the Glenora/Stoney Creek Neighbourhood Connection east of Adelaide will be completed at a later date.



Additional Connectivity



- Protected Bike Lane
- Thames Valley Parkway
- Multi-Use Pathway
- Bike Lane
- Signed Route or Sharrows

Base Map:
City of London
Walk and Bike Map (2022)

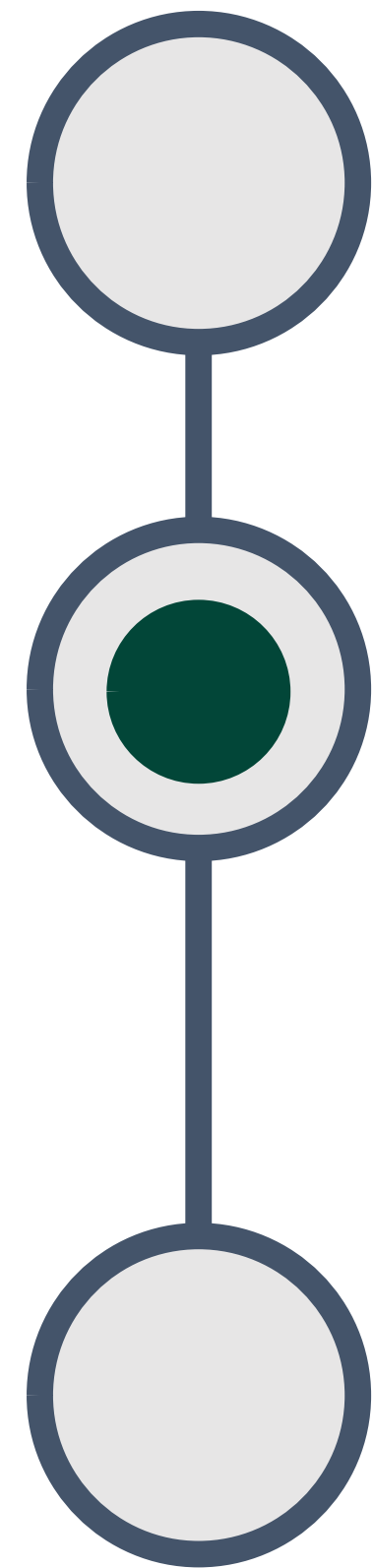
In addition to connecting the Stoney Creek Pathway to the TVP North Branch, the new multi-use pathway will connect to other parks and existing cycling infrastructure, including:

- Windermere Fields Park
- Stoney Creek Meadows Park
- North London Athletic Fields
- Windermere Road Bike Lanes
- Adelaide Street Protected Bike Lanes
- Kipps Lane Bike Lanes



Timeline

Project Timeline



Phase 1: Preliminary Design

Completed August 2023

Phase 2: Detailed Design

October 2023 to May 2024

Phase 3: Construction

Summer / Fall 2024



Funding

Active Transportation
Fund **Canada**



- 60% funded by the Federal Government's Active Transportation Fund
- 40% funded by the City of London



The City acknowledges and appreciates this opportunity to work with the federal government to improve walking and cycling comfort and connectivity.



Archaeology and Natural Heritage



Archaeology

As recommended in the EA, a Stage 2 Archaeological Assessment was conducted within the project limits. Field surveys were completed in November 2023.

The Stage 2 assessments did not result in the documentation of any archaeological resources. The project area can be considered free of archaeological concern and no further archaeological assessment is recommended at this time.



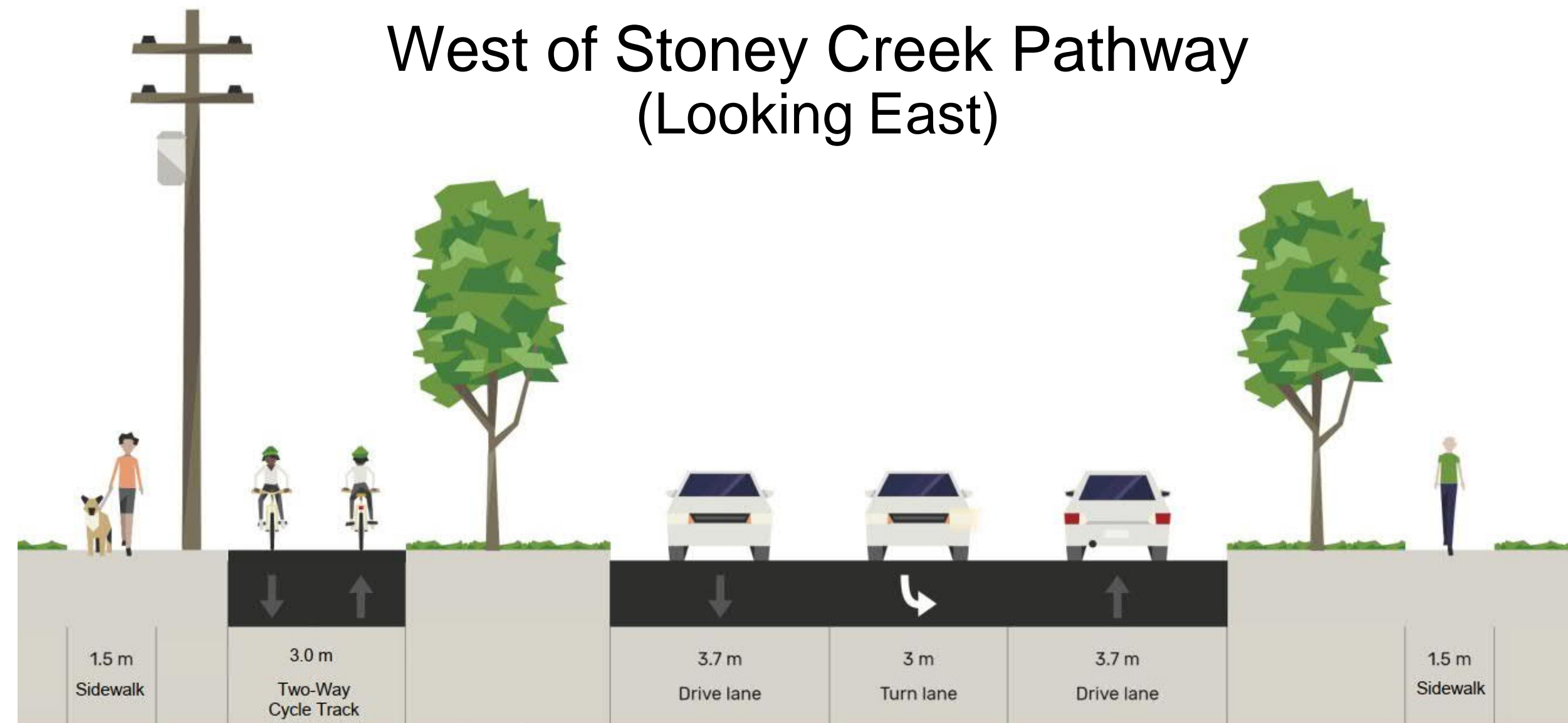
Natural Heritage and Tree Impacts

The woodlands north of Windermere Road are a designated Natural Heritage Area. Accordingly, any construction next to the woodland will be limited to within the existing paved portions of the roadway, with no encroachment into the woodlands. Some trimming of tree limbs may be necessary.

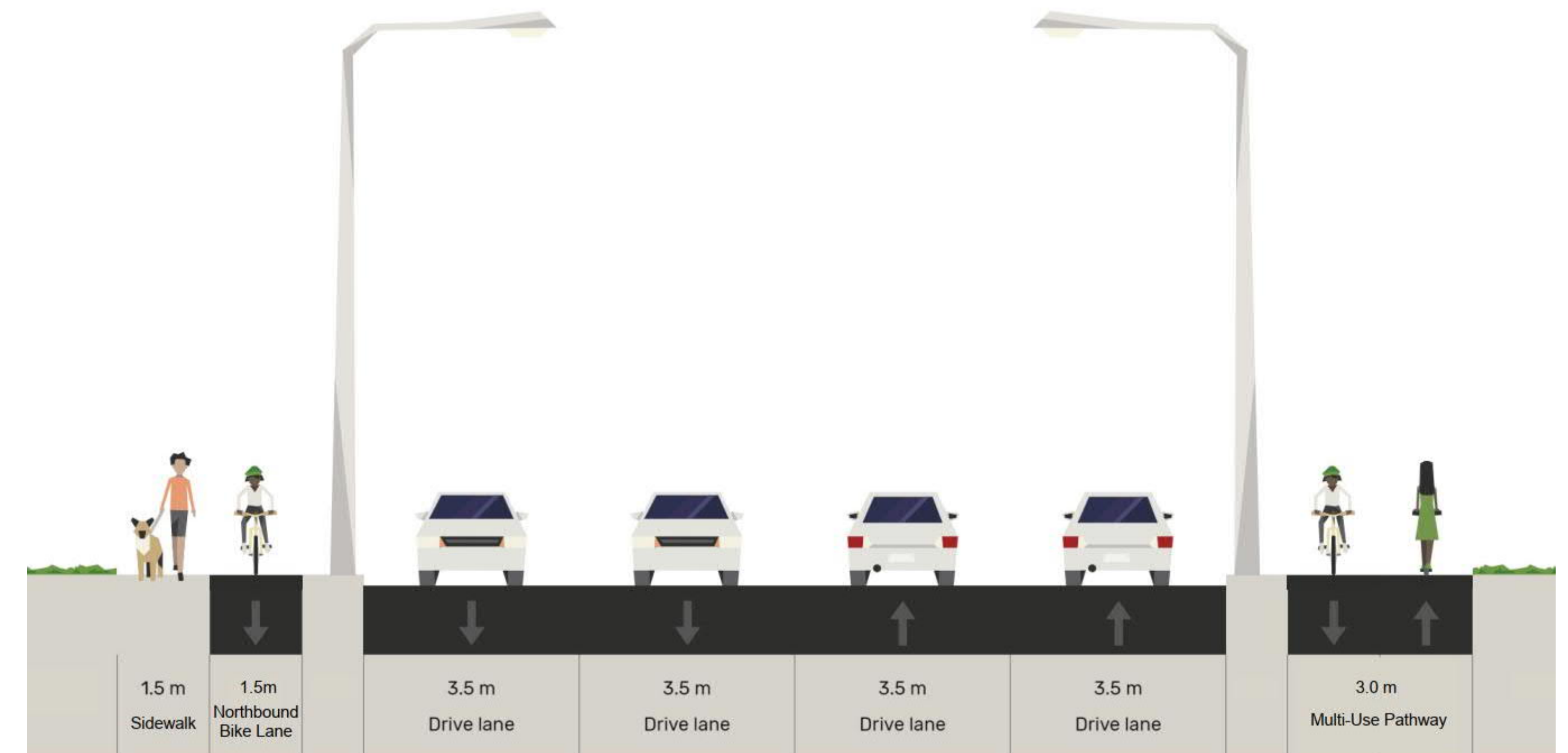
Removal of smaller sized trees are planned outside the natural heritage area, including street trees along Windermere Road, and some trees in North London Athletic Fields where the pathway connection is made to the TVP. Where practical these trees will be replaced with new trees in nearby locations.

Typical Cross Sections

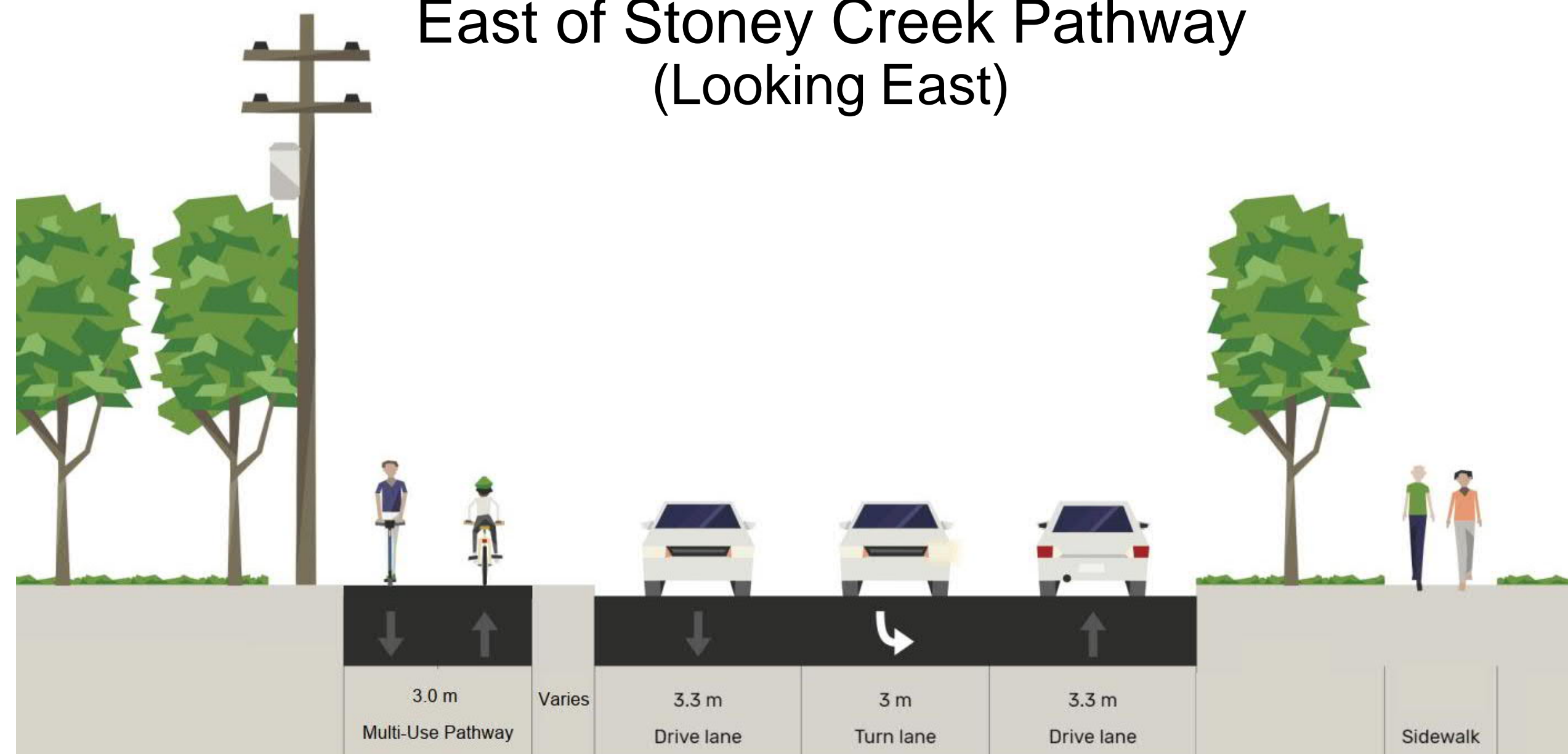
Windermere Road
West of Stoney Creek Pathway
(Looking East)



Adelaide Street
South of Windermere Road
(Looking South)

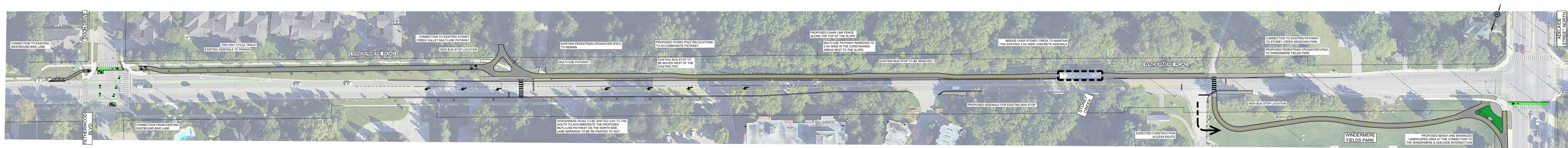


Windermere Road
East of Stoney Creek Pathway
(Looking East)





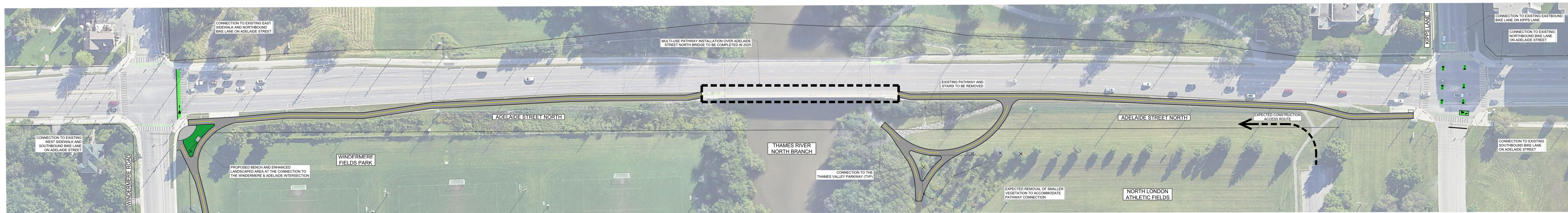
Windermere Road



Preliminary roll plan provided as a separate file



Adelaide Street



Preliminary roll plan provided as a separate file